



ELC 4351:
Digital Signal
Processing

Liang Dong

Quantization
Errors

Signal
Quantization

Signal to
Quantization
Noise Ratio

Coefficient
Quantization

Roundoff
Noise

Overflow

Scaling of
Signals

ELC 4351: Digital Signal Processing

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Quantization Errors

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Errors in Computing Systems:

- Numbers are represented by a finite number of bits. The resulting errors are called the finite-wordlength or finite-precision effects.



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Errors in Computing Systems:

- Numbers are represented by a finite number of bits. The resulting errors are called the finite-wordlength or finite-precision effects.
- Quantization errors:
 - Signal quantization
 - Coefficient quantization



Quantization Errors

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Errors in Computing Systems:

- Numbers are represented by a finite number of bits. The resulting errors are called the finite-wordlength or finite-precision effects.
- Quantization errors:
 - Signal quantization
 - Coefficient quantization
- Arithmetic errors:
 - Roundoff or truncation
 - Overflow



Signal Quantization

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Scaling of
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- Analog signal $x(t) \Rightarrow$ ADC \Rightarrow digital signal $x[n]$.



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Scaling of
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- Analog signal $x(t) \Rightarrow \text{ADC} \Rightarrow$ digital signal $x[n]$.
- First, $x(t)$ is sampled and becomes a discrete-time signal $x(nT)$.



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Scaling of
Signals

- Analog signal $x(t) \Rightarrow \text{ADC} \Rightarrow$ digital signal $x[n]$.
- First, $x(t)$ is sampled and becomes a discrete-time signal $x(nT)$.
- Then, $x(nT)$ is encoded using B bits and becomes a digital signal $x[n]$.



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Scaling of
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- Suppose that $-1 \leq x[n] < 1$.



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Scaling of
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- Suppose that $-1 \leq x[n] < 1$.
- Dynamic range = 2.



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Scaling of
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- Suppose that $-1 \leq x[n] < 1$.
- Dynamic range = 2.
- B bits represent a sample, the number of quantization levels is 2^B .



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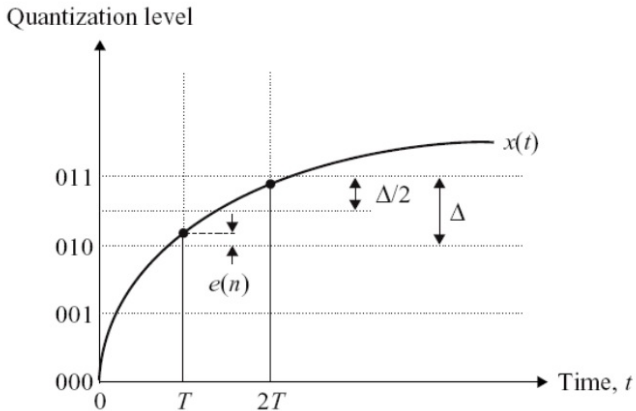
Scaling of
Signals

- Suppose that $-1 \leq x[n] < 1$.
- Dynamic range = 2.
- B bits represent a sample, the number of quantization levels is 2^B .
- The quantization step (resolution): $\Delta = \frac{2}{2^B} = 2^{-B+1}$.



Rounding for Quantization

A 3-bit ADC:





Rounding Error

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Scaling of
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- Quantization error/noise: $e(n) = x(n) - x(nT)$.



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Scaling of
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- Quantization error/noise: $e(n) = x(n) - x(nT)$.
- Rounding: $|e(n)| \leq \Delta/2$.



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- Quantization error/noise: $e(n) = x(n) - x(nT)$.
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- The quantization noise depends on the quantization step.



Rounding Error

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Scaling of
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- Quantization error/noise: $e(n) = x(n) - x(nT)$.
- Rounding: $|e(n)| \leq \Delta/2$.
- The quantization noise depends on the quantization step.
- More bits \Rightarrow smaller quantization step \Rightarrow lower quantization noise.



Linear Model

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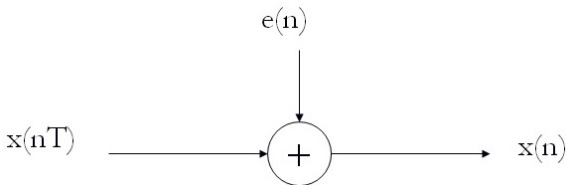
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Scaling of
Signals

- The nonlinear operation of quantizer: $x(n) = Q[x(nT)]$
- Linear operation: $x(n) = Q[x(nT)] = x(nT) + e(n)$





Common Assumptions

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Scaling of
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- Assume that the quantization error $e(n)$ is uncorrelated with $x(n)$.



Common Assumptions

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Scaling of
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- Assume that the quantization error $e(n)$ is uncorrelated with $x(n)$.
- Assume $e(n)$ is a random variable uniformly distributed in the interval $[-\Delta/2, \Delta/2]$.



Common Assumptions

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Scaling of
Signals

- Assume that the quantization error $e(n)$ is uncorrelated with $x(n)$.
- Assume $e(n)$ is a random variable uniformly distributed in the interval $[-\Delta/2, \Delta/2]$.
- Therefore, $E[e(n)] = (-\Delta/2 + \Delta/2)/2 = 0$;

$$\text{and variance: } \sigma_e^2 = \frac{\Delta^2}{12} = \frac{2^{-2B}}{3}.$$

Large wordlength B leads to small quantization error σ_e^2 .



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- $\text{SNR} = 10 \log_{10}(\sigma_x^2 / \sigma_e^2)$.



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Scaling of
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- $\text{SNR} = 10 \log_{10}(\sigma_x^2/\sigma_e^2)$.

- With $\sigma_e^2 = 2^{-2B}/3$, we have

$$\begin{aligned}\text{SNR} &= 10 \log_{10}(3 \times 2^{2B} \sigma_x^2) \\ &= 10 \log_{10} 3 + 20B \log_{10} 2 + 10 \log_{10} \sigma_x^2 \\ &= 4.77 + 6.02B + 10 \log_{10} \sigma_x^2\end{aligned}$$



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- For each additional bit, the ADC provides about 6-dB gain.



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- For each additional bit, the ADC provides about 6-dB gain.
- SNR is proportional to σ_x^2 . Keep signal power as large as possible.



Coefficient Quantization

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Scaling of
Signals

- The filter coefficients b_n , a_m are quantized for a given fixed-point processor.



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Scaling of
Signals

- The filter coefficients b_n , a_m are quantized for a given fixed-point processor.
- Coefficient quantization can cause serious problems if the poles of designed IIR filters are too close to the unit circle.



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Scaling of
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- The filter coefficients b_n , a_m are quantized for a given fixed-point processor.
- Coefficient quantization can cause serious problems if the poles of designed IIR filters are too close to the unit circle.
- This is because those poles may move outside the unit circle due to coefficient quantization, resulting in an unstable implementation.



Roundoff Noise

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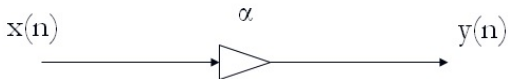
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Scaling of
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■ $y(n) = \alpha x(n)$



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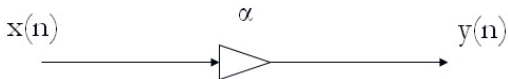
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Scaling of
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- $y(n) = \alpha x(n)$
- $x(n)$ and α are B -bit, the product $y(n)$ will be $2B$ -bit.



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Scaling of
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- $y(n) = \alpha x(n)$
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- Usually, the result will be stored in B -bit memory.



Roundoff Noise

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- Truncation or rounding brings the roundoff noise.



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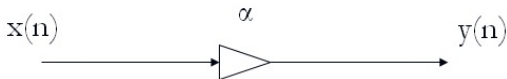
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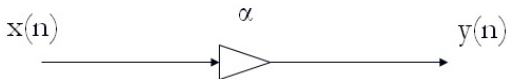
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Scaling of
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- Usually, the result will be stored in B -bit memory.
- Truncation or rounding brings the roundoff noise.
- $y(n) = Q[\alpha x(n)] = \alpha x(n) + e(n)$
- Is this noise larger?



Overflow

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Scaling of
Signals

- When the dynamic range of signals is fixed, the result of an arithmetic addition may exceed the capacity of the register.



Overflow

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Scaling of
Signals

- When the dynamic range of signals is fixed, the result of an arithmetic addition may exceed the capacity of the register.
- This overflow results in severe distortion of the signal output.



Overflow

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Scaling of
Signals

- When the dynamic range of signals is fixed, the result of an arithmetic addition may exceed the capacity of the register.
- This overflow results in severe distortion of the signal output.
- We need saturation algorithm or proper scaling.



Saturation Algorithm

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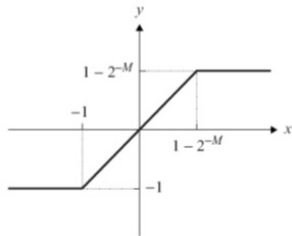
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Scaling of
Signals

- Saturation arithmetic prevents overflow by keeping the result at a maximum value.
- Saturation algorithm is a nonlinear operation that clips the desired waveform.



$$y = \begin{cases} 1 - 2^{-M}, & x \geq 1 - 2^{-M} \\ x, & -1 \leq x < 1 - 2^{-M} \\ -1, & x < -1 \end{cases}$$



Scaling of Signals

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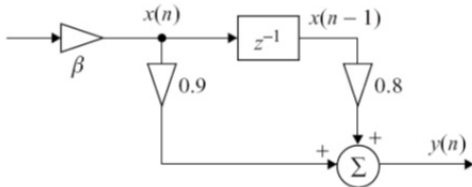
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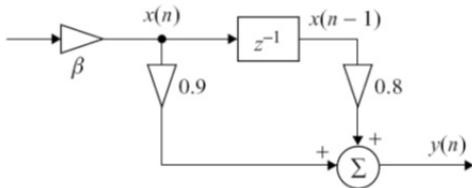
- An effective technique in preventing overflow is by scaling down the signal.





Scaling of Signals

- An effective technique in preventing overflow is by scaling down the signal.



- If the signal $x(n)$ is scaled by β , the corresponding signal variance changes to $\beta^2 \sigma_x^2$.



Scaling of Signals

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 $= 4.77 + 6.02B + 10 \log_{10} \sigma_x^2 + 20 \log_{10} \beta$
- For down scaling, $\beta < 1$.



Scaling of Signals

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- The term $20 \log_{10} \beta$ is negative, and the SNR reduces.



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- For example, when $\beta = 0.5$, $20 \log_{10} \beta = -6.02$ dB, thus reducing the SNR of the input signal by about 6 dB.



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- For example, when $\beta = 0.5$, $20 \log_{10} \beta = -6.02$ dB, thus reducing the SNR of the input signal by about 6 dB.
- This is equivalent to losing 1 bit in representing the signal. Why?